# **Motorized Capacitor**

## **Step/Direction – CW/CCW-Interface**



#### **Document Information**

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#### Step / Direction - CW / CCW - Interface

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#### **Document history**

Doc. Rev.	Date	Author(s)	Change(s)	Status
1.0	2007-03-30	O. Lehmann	Initial document	released
1.1	2010-06-25	A. Renggli	Various additions	internal
02	2014-01-29	W. Bigler / T. Fenske	Reviewed with minor modifications / configuration section added	released

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## **Overview of Service Bulletins for Integrated Drives (ID)**

SB-60	Overview of Integrated Drives
SB-61	Drive Unit
SB-62	Introduction to Stepping Motors     Principal function of stepper motors     Control system of the drive unit
SB-63	Electrical Installation ID-400 • Stepping driver control signals and connections for EXPERT ID
SB-64	Electrical Installation ID-1200 • Stepping driver control signals and connections for EXPERT ID
SB-65	Electrical Installation ID-2800 • Stepping driver control signals and connections for EXPERT ID
SB-66	Electrical Installation ID-5400 • Stepping driver control signals and connections for EXPERT ID
SB-67	Step/Direction; Clockwise / Counter clockwise (CW/CCW) Interface
SB-68	Software Protocol Interface RS-232
SB-69	Software Protocol Interface RS-485
SB-72	Safety Aspects of Integrated Drives

**DATA SHEETS** are available for each Integrated Drive

#### 1 Step/Direction CW/CCW Interface

# 1.1 Stepping driver signals for step/direction and clockwise/ counter clockwise interfaces

If a stepping motor driver is used, there are typically two alternatives for the input signals: "pulse & direction" and "Clockwise/Counterclockwise". The respective signals are shown in figures 1 and 2 respectively. Each full signal cycle results in one step of the stepping motor.

For "pulse & direction" the "pulse signal" is the trigger for each pulse and the "direction signal" provides the rotating direction for the motor.

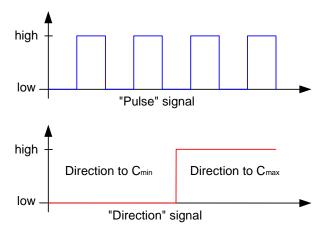


Fig. 1: Definition of the "pulse & direction" signals

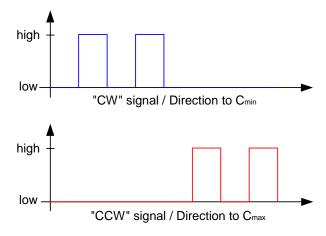


Fig. 2: Definition of the "Clockwise/Counterclockwise" signals

#### 1.2 Stepping Driver Timing Diagram

When stepping motor control signals are used to control the motion of the stepping motor, the following are the required timing diagram conditions:

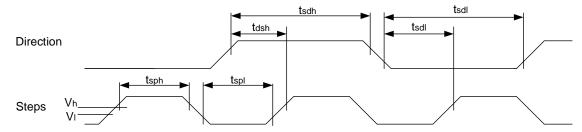


Fig. 3: Definition of the timing diagram at the stepper driver inputs

Symbol	Parameter	Min	Тур	Max	Units
t sph	Minimum pulse width, step high	250			nS
t spl	Minimum pulse width, step low	250			nS
t sdh	Minimum pulse width, direction high	250			nS
t sdl	Minimum pulse width, direction low	250			nS
t <sub>dsh</sub>	Direction - high Steps	125			nS
t <sub>dsl</sub>	Direction - low Steps	125			nS
VI	Input Low Voltage	-0.5		1.5	V
$V_h$	Input High Voltage	3.5		5.5	V

Fig. 4: Definition of the timing diagram at the stepper driver input

#### 2 Reference drive

By connecting pin 7, X2 (see SB-63) to a high voltage state (3.5 – 5.5Volts) the ID will do a reference drive. This feature is available from driver software version V.1.1.0.

## 3 Revision history

Changes from document SB-67 V.1.1 to SB-67 Rev. 02:

Section	Description of change	
General	Updated layout	